

Introduction to Finite Difference Methods for Option Pricing

Finite Difference Methods



The price of a European option P(S, t) is solution of the Black-Scholes PDE:

$$rac{\partial P}{\partial t} + r \cdot rac{\partial P}{\partial S} \cdot S + rac{1}{2} \cdot \sigma^2 \cdot S^2 \cdot rac{\partial^2 P}{\partial S^2} = r \cdot P$$

with the final condition, with f the payoff of the option:

$$P(S,T) = f(S_T)$$

In most cases we do not have a closed form solution of this equation.

We need to apply numerical methods to solve it.

Finite Difference Methods



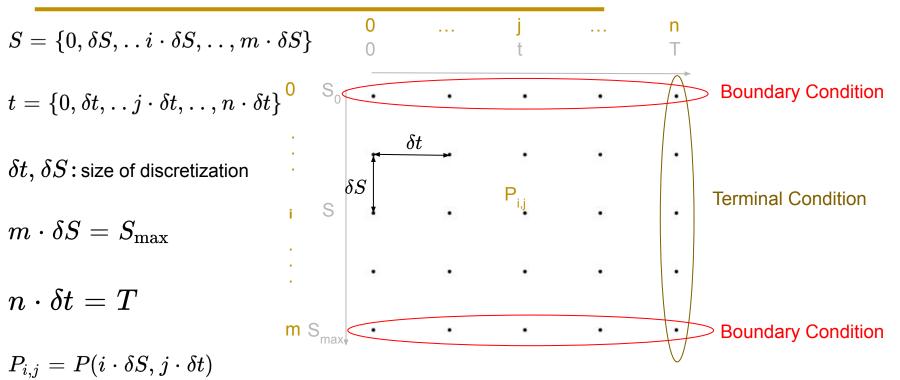
Finite-difference methods (**FDM**) is the generic term for a large number of techniques that can be used for solving differential equations, approximating derivatives with finite differences.

It consists of a **discretization** of both spatial (underlying price in our case) and time intervals to obtain a finite **grid**.

We find solutions for a differential equation by **approximating** every partial derivative with **numerical methods** and we apply the solution to the points of the grid.



2-Dimensional Grid



Finite Difference Approximations



Let's consider a function f continuous and n times differentiable, we derive the following **approximation** for f(x+h) from **Taylor**:

$$f(x+h)=f(x)+h\cdot f'(x)+rac{h^2}{2}\cdot f''(x)+\dotsrac{h^n}{n!}\cdot f^{(n)}(x)+oldsymbol{O}(h^{n+1})$$
 Order of the error



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$$f(x+h)=f(x)+h\cdot f'(x)+rac{h^2}{2}\cdot f''(x)+\ldotsrac{h^n}{n!}\cdot f^{(n)}(x)+Oig(h^{n+1}ig)$$
 Order of the error

$$f'(x)=rac{f(x+h)-f(x)}{h}+O(h)$$

This is the forward difference approximation of the first derivative.



Similarly we have:

$$f(x-h) = f(x) - h \cdot f'(x) + rac{h^2}{2} \cdot f'\,'(x) + rac{(-1)^n}{n!} \cdot f^{(n)}(x) + Oig(h^{n+1}ig)$$

$$f'(x)=rac{f(x)-f(x-h)}{h}+O(h)$$

This is the backward difference approximation of the first derivative.



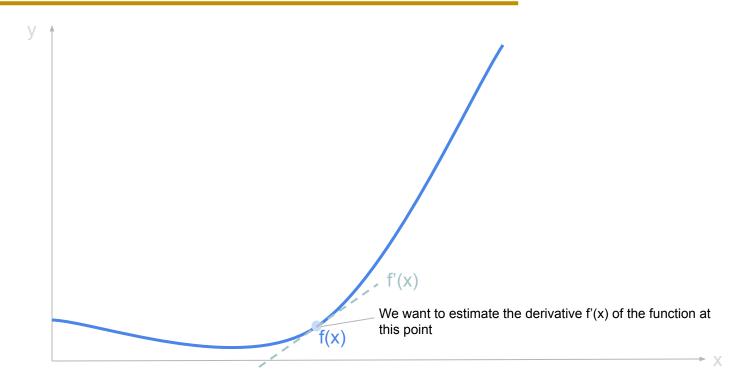
By subtracting the two developments and dividing it by 2.h we get:

$$f'(x) = rac{f(x+h)-f(x-h)}{2\cdot h} + Oig(h^2ig)$$

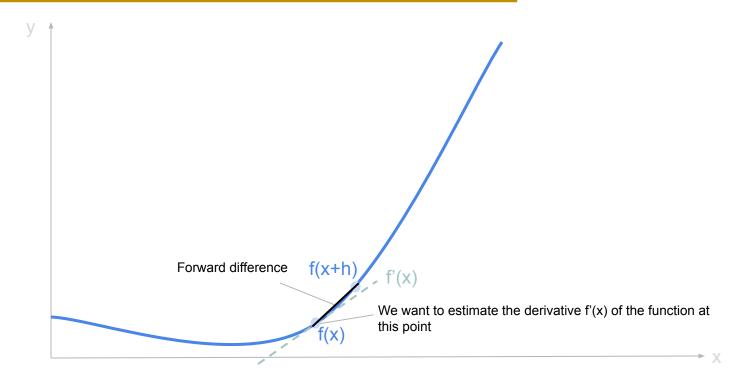
This is the central difference approximation for the first derivative.

It is the best of the three approximation with an error in h^2 vs h for the two others.

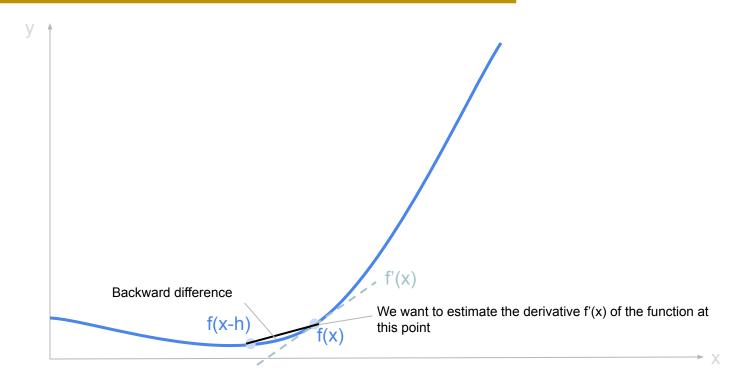




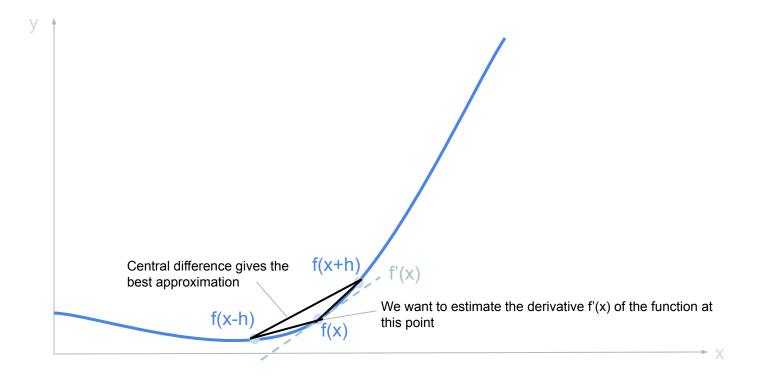












Finite Difference Approximations Second Order



We also get the approximation of the second derivatives by adding the two developments and dividing by h^2 .

$$f$$
 '' $(x) = rac{f(x+h) - 2 \cdot f(x) + f(x-h)}{h^2} + Oig(h^2ig)$

This is the second-order central difference approximation for the second derivative.

The error is in h^2 .

Finite Difference Approximations



From the Black Scholes PDE, we need approximations for:

$$rac{\partial P}{\partial t} + r \cdot rac{\partial P}{\partial S} \cdot S + rac{1}{2} \cdot \sigma^2 \cdot S^2 \cdot rac{\partial^2 P}{\partial S^2} = r \cdot P$$

Forward Difference Backward Difference Central Difference

 $\begin{array}{lll} \begin{array}{lll} \frac{\partial P}{\partial t} = \frac{P_{i,j+1} - P_{i,j}}{\delta t} & \frac{\partial P}{\partial S} = \frac{P_{i+1,j} - P_{i,j}}{\delta S} \\ \begin{array}{lll} \frac{\partial P}{\partial t} = \frac{P_{i,j} - P_{i,j-1}}{\delta t} & \frac{\partial P}{\partial S} = \frac{P_{i,j} - P_{i-1,j}}{\delta S} \\ \end{array} \\ \begin{array}{ll} \frac{\partial P}{\partial t} = \frac{P_{i,j+1} - P_{i,j-1}}{2 \cdot \delta t} & \frac{\partial P}{\partial S} = \frac{P_{i+1,j} - P_{i-1,j}}{2 \cdot \delta S} \end{array} \end{array}$

Second-order
$$rac{\partial^2 P}{\partial S^2} = rac{P_{i+1,j} - 2 \cdot P_{i,j} + P_{i-1,j}}{\delta S^2}$$

Using grid notations

Terminal Conditions



At its expiration, the price of an option is equal to its final payoff:

ContinuousDiscrete $P(S,T) = f(S_T)$ $P_{i,n} = f(i \cdot \delta S)$ Call Option $P(S,T) = (S_T - K)^+$ $P_{i,n} = (i \cdot \delta S - K)^+$

Put Option $P(S,T) = (K - S_T)^+$ $P_{i,n} = (K - i \cdot \delta S)^+$



Boundary Conditions

Dirichlet Boundary Condition (Type I)

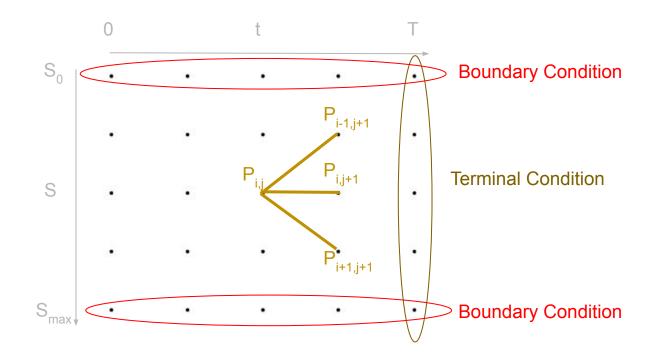
Call OptionPut OptionP(0,t) = 0 $P(S_{\max},t) = S_{\max} - K \cdot e^{-r \cdot (T-t)}$ $P(0,t) = K \cdot e^{-r \cdot (T-t)}$ $P(S_{\max},t) = 0$ $P_{0,j} = 0$ $P_{m,j} = m \cdot \delta S - K \cdot e^{-r \cdot (n-j) \cdot \delta t}$ $P_{0,j} = K \cdot e^{-r \cdot (n-j) \cdot \delta t}$ $P_{m,j} = 0$

Neumann Boundary Condition (Type II)

 $egin{aligned} &rac{\partial^2 P}{\partial S^2}(\delta S,t)=0 & &rac{\partial^2 P}{\partial S^2}((m-1)\cdot\delta S,t)=0 \ &P_{0,j}-2\cdot P_{1,j}+P_{2,j}=0 & &P_{m-2,j}-2\cdot P_{m-1,j}+P_{m,j}=0 \end{aligned}$

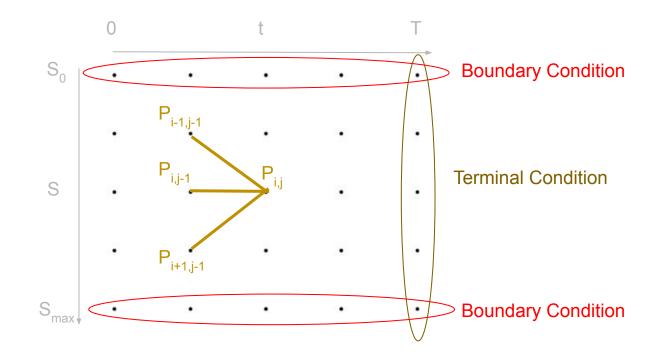


Explicit Method



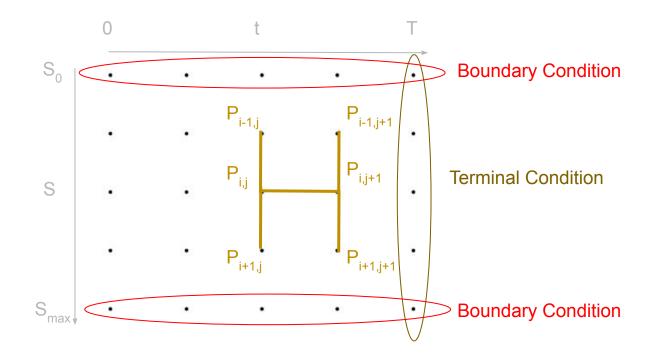


Implicit Method





Crank-Nicolson Method





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